

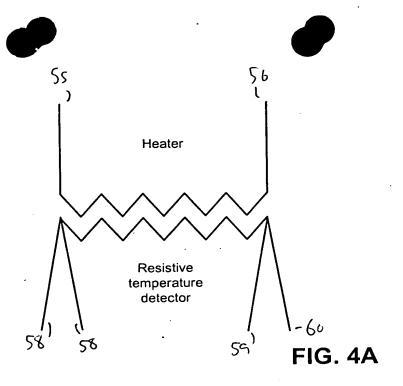
FIG. 2

Laboratory robot

Data acquisition and control (DAQ) board

FIG 3A

FIG. 3B



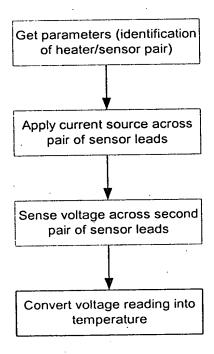


FIG. 4B

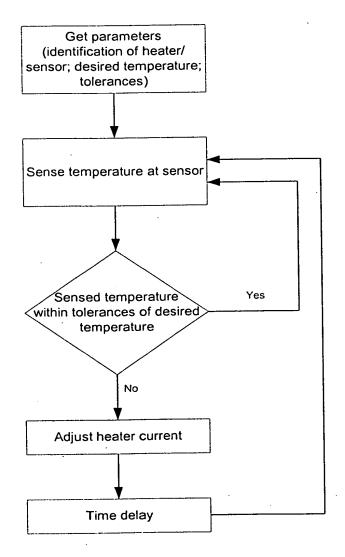
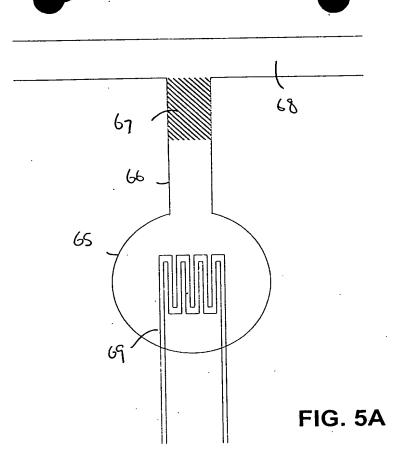


FIG. 4C



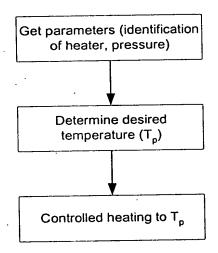


FIG. 5B

S. 17.00.

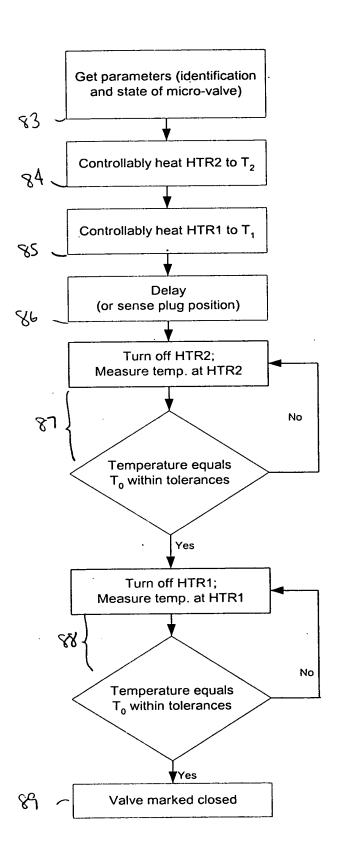


FIG. 6C

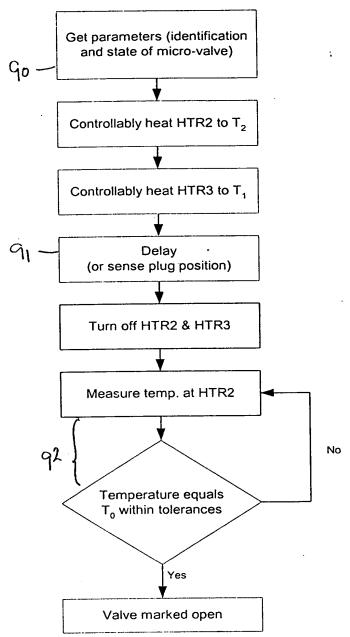
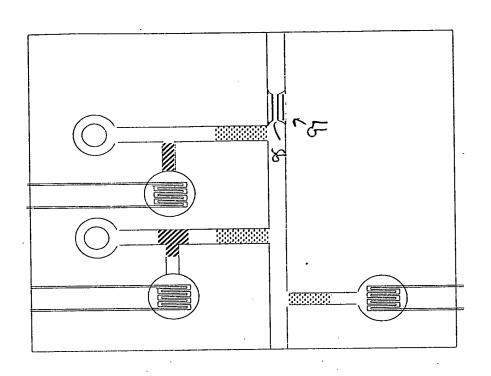


FIG. 6D

KENTY



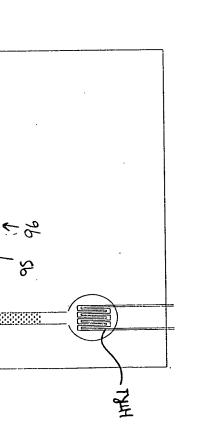
81

Y ALVEZ

120701

FIG. 7A

FIG. 7B



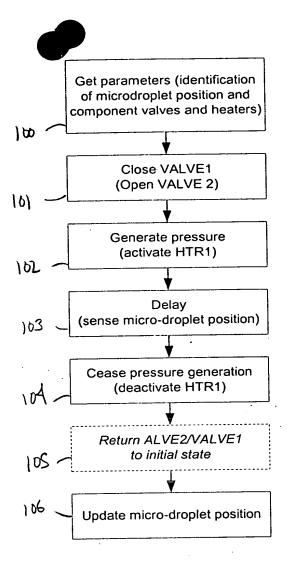
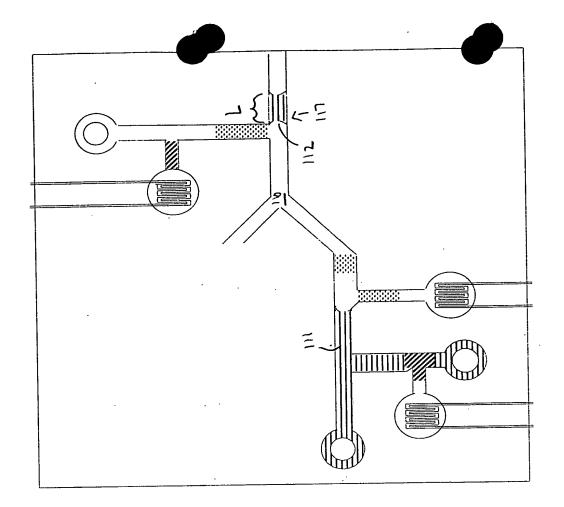


FIG. 7C



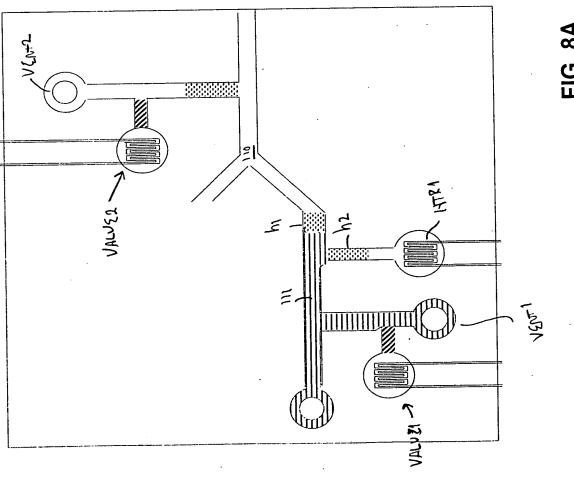
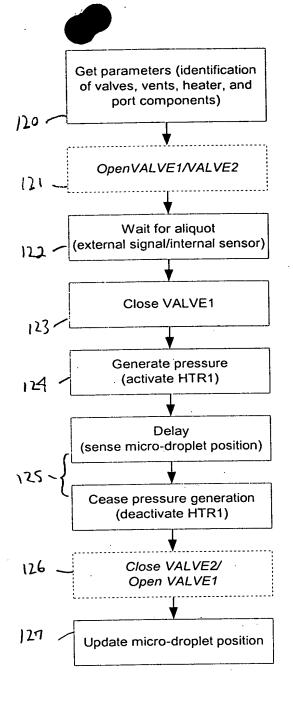


FIG. 8A

FIG. 8B



PORTI -- III

FIG. 8D

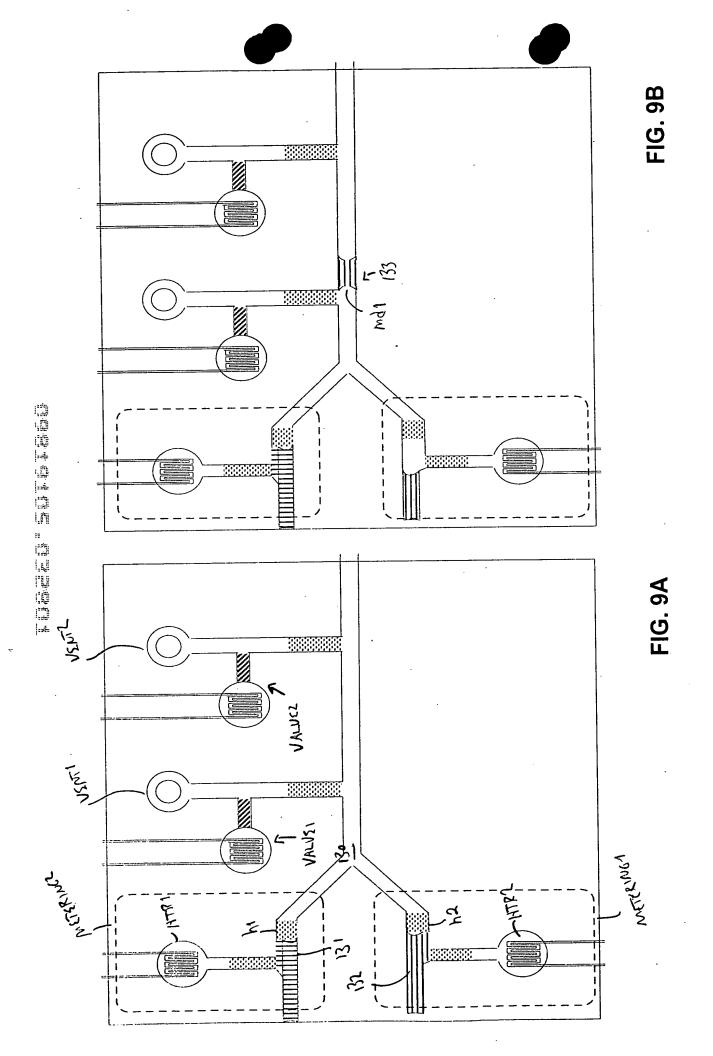


FIG. 9C

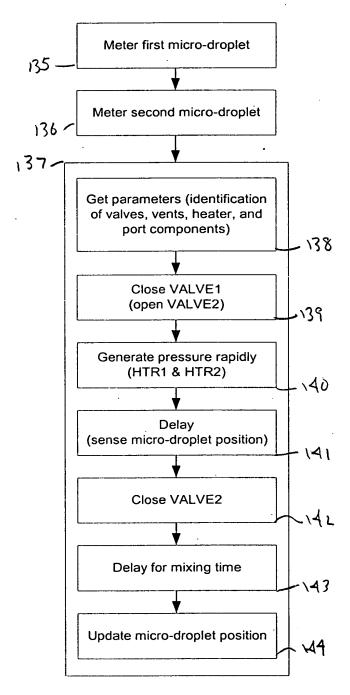
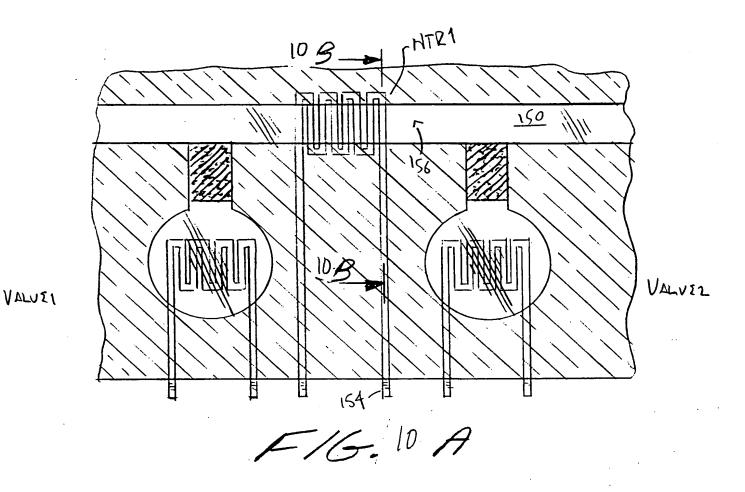
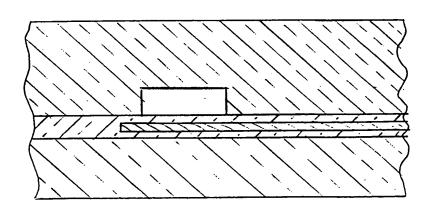


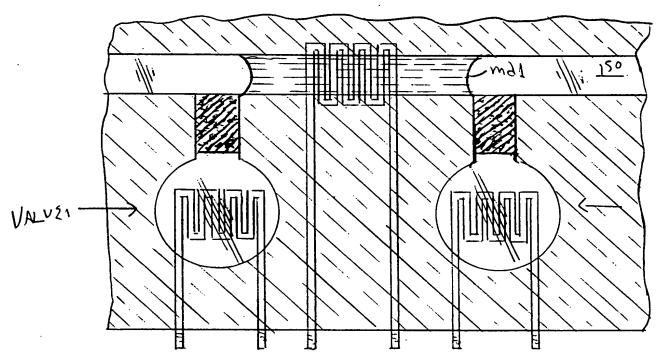
FIG. 9E



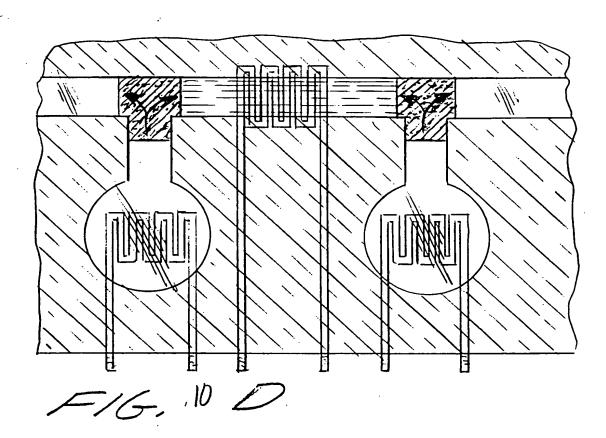


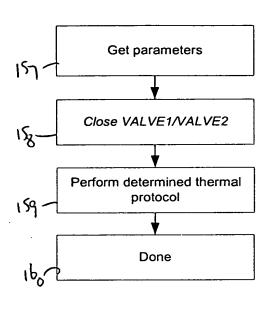
F16.10B

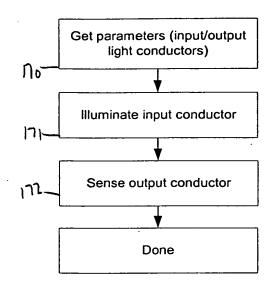
## F16, 10°C



VALUEL

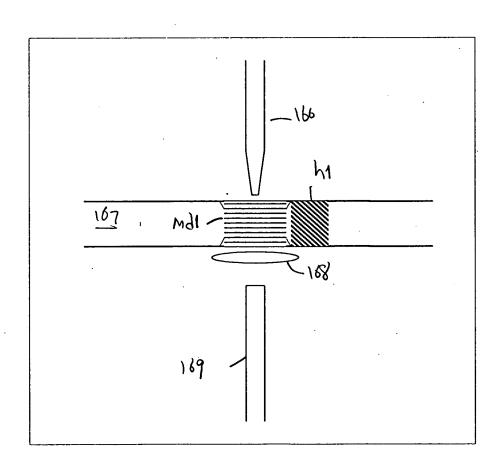




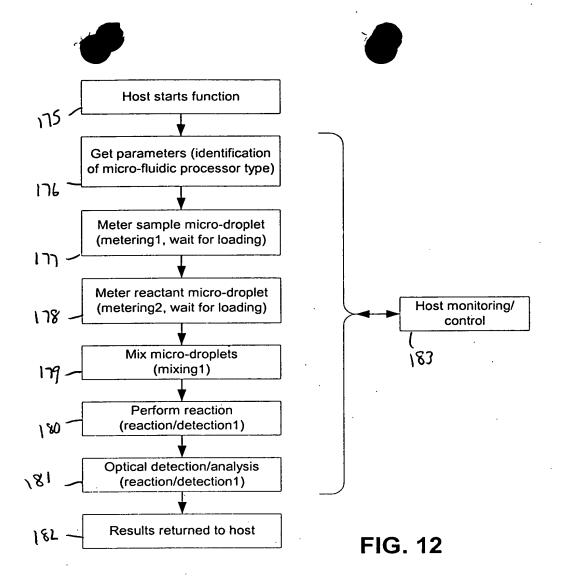


**FIG. 10E** 

FIG. 11B



**FIG. 11A** 



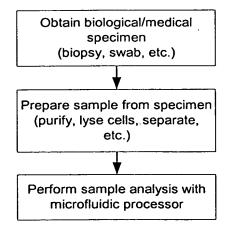


FIG. 13